# Übersichtskarte / Fahrzeugstatus

The map shows the last position of all your vehicles or a certain group of vehicles. Below the map, you will see a table which contains the last position for each vehicle and detailed information about it.

Under certain circumstances it is possible that this position does not coincide with the actual position of the vehicle. This might for example be the case if the box could not send data via GPRS for a long period of time and begins to empty its message memory.

Index		
<ul> <li>Group selection</li> <li>Map navigation <ul> <li>Zoom</li> <li>Navigation</li> <li>Map type</li> <li>Toolbar</li> <li>Vehicle list</li> </ul> </li> <li>Main actions</li> <li>Vehicle status</li> </ul>		

# Group selection

If you only want to see a certain group of vehicles, proceed as follows:

- Select an entry from the "group" selection box or
- Enter the name of the group in the input field with the selection box open and select an entry from the filtered list.

# Map navigation

Within the map there are various means and methods available to optimize and / or narrow down the information you require.

#### Zoom



#### Navigation



#### Map type



#### Toolbar



R	Switching "Vehicle grouping" on /off
2	Switch AutoZoom on / off
-th	Enable / disable rectangle zoom
T	Apply filter
Q	Search adresses
$\bigstar$	map favorites
1	Switch "ShowAdresses" on /off
×	Map settings
$\times$	Load map in full screen

#### Vehicle list



### Main actions

There are several global actions available in the entire module "Overview map / vehicle status". These are displayed as a drop-down button in the upper right corner of the map.



By clicking on the arrow of the button, a menu opens, in which the various actions can then be selected and executed or started.

0	Reload map overview	Reloads the map and the table with the vehicle data
0	Open popup	Opens the overview map and the vehicle status table in a common new popup (window)

### Vehicle status

The table shows a certain number of entries, depending on the setting. The number can be temporarily adjusted directly in the tab head. There is also a search field on the right above the table, which is used to search for specific vehicles. Furthermore, the data can be sorted ascending or descending depending on the column.

The number of columns depends on the available data of the vehicles. As soon as a vehicle delivers data to a particular column, it is displayed in the table. However, certain columns are always available. Vehicles for which there are no current position messages are displayed in the table with the entry "No position present".

The following columns can appear in the table in this order:

Nr.	Column description	Description	Optional
1		Vehicle icon with ignition status	no
2	object name	Name of the vehicle	no
3		Advanced status message	yes

4	driver	Name of the current driver	yes
5	date	Date and time of the last position message	no
6	position	Address or name of the last known position	no
7	driving time	driving time of the current day	yes
8	steering time	Recorded steering time of the current day	yes
9	Analogue 1	Analog input number 1	yes
10	Analogue 2	Analog input number 2	yes
11	Analogue 3	Analog input number 3	yes
12	Analogue 4	Analog input number 4	yes
13	Euroscan 1	Euroscan input number 1	yes
14	Euroscan 2	Euroscan input number 2	yes
15	Euroscan 3	Euroscan input number 3	yes
16	Euroscan 4	Euroscan input number 4	yes
17	Euroscan 5	Euroscan input number 5	yes
18	Euroscan 6	Euroscan input number 6	yes
19	Euroscan 7	Euroscan input number 7	ja
20	Euroscan 8	Euroscan input number 8	ja
21	est. arrivaltime	Expect time of arrival at the current navigation destination	ja
22	remaining time	Remaining travel time to the current navigation destination	ja
23	remaining distance	Remaining distance to the current navigation destination	ja
24	targetposition	Current navigation target	ja